An improved convergence analysis of a superquadratic method for solving generalized equations

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ABSTRACT. We provide a finer local convergence analysis than before [6]–[9] of a certain superquadratic method for solving generalized equations under Hölder continuity conditions.

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RESUMEN. Nosotros hacemos un análisis de convergencia local más fino que el proporcionado antes de [6]–[9] de cierto método supercuadrático para resolver ecuaciones generalizadas bajo ciertas condiciones de continuidad de Hölder.

1. Introduction

In this study we are concerned with the problem of approximating a solution x^* of the generalized equation of the form

$$o \in F(x) + G(x), \tag{1.1}$$

where F is a twice Fréchet differentiable operator defined on a Banach space X with values in a Banach space Y, and G is a set-valued map from X to the subsets of Y.

Local results providing sufficient conditions for the existence of x^* have been provided by several authors using various iterative methods and hypotheses [2]–[9], [11]. Here in particular, we use the method

$$o \in F(x_n) + \nabla F(x_n)(x_{n+1} - x_n) + \frac{1}{2}\nabla^2 F(x_n)(x_{n+1} - x_n)^2 + G(x_{n+1})$$
 (1.2)

to generate a sequence approximating x^* .

In the paper by Geoffroy and Pietrus [9] local convergence results were provided for method (1.2) using Hölder continuity conditions on $\nabla^2 F$. Here we are motivated by this paper, our paper [1], and optimization considerations.

In particular using the same hypotheses but more precise error bounds we provide a larger convergence radius and finer error bounds on the distances $||x_n - x^*||$ $(n \ge 0)$.

Some numerical examples are provided to justify our theoretical results. The same examples are used to compare favorably our results with the corresponding ones in [9].

The paper is organized as follows: In Section 2 we have collected a number of necessary results [6], [9], [10] needed in our local convergence analysis appearing in Section 3.

2. Preliminaries

We need a definition about the Aubin continuity [5]–[7]:

Definition 2.1. A set-valued map $\Gamma: X \to Y$ is said to be M-pseudo-Lipschitz around $(x_0, y_0) \in graph \ F = \{(x, y) \in X \times Y \mid y \in \Gamma(x)\}$ if there exist neighborhoods V of x_0 and U of y_0 such that

$$\sup_{y \in \Gamma(u) \cap U} \operatorname{dist}(y, \Gamma(v)) \le M \|u - v\| \text{ for all } x, y \in V.$$
 (2.1)

The Aubin continuity of Γ is equivalent to the openess with linear rate of Γ^{-1} and the metric regularity of Γ^{-1} .

Let A and C be two subsets of X. Then the excess e from the set A to the set C is given by

$$e(C,A) = \sup_{x \in C} \operatorname{dist}(x,A). \tag{2.2}$$

Estimate (2.1) using (2.2) can be written

$$c\left(\Gamma(u) \cap U, \Gamma(v)\right) \le M\|u - v\| \text{ for all } u, v \in V. \tag{2.3}$$

We also need a lemma about fixed points [10]:

Lemma 2.2. Let (X, ρ) be a Banach space, let T be a map from X into the closed subsets of X, let $p \in X$ and let r and λ be such that $0 \le \lambda < 1$, and

$$\operatorname{dist}(p, T(p)) \le r(1 - \lambda), \tag{2.4}$$

$$e(T(u) \cap U(p,r), T(v)) \le \lambda \rho(u,v), \text{ for all } u,v \in U(p,r)$$
 (2.5)

where

$$U(p,r) = \{ x \in X \ ||x - p|| \le r \}. \tag{2.6}$$

Then T has a fixed point in U(p,r). Moreover if T is single-valued, then x is the unique fixed point of T in U(p,r).

Let x^* be a solution of (1.1). We assume:

- (A1) F is Fréchet-differentiable on some neighborhood V of x^* ;
- (A2) $\nabla^2 F$ is bounded by L on V and $\|\nabla^2 F(x^*)\| \leq L_0$;

(A3) $\nabla^2 F$ is α -Hölder on V with constant K, i.e.

$$\|\nabla^2 F(x) - \nabla^2 F(y)\| \le K \|x - y\|^{\alpha} \text{ for all } x, y \in V,$$
 (2.7)

where K satisfies

$$K \ge 5(\alpha+1)(\alpha+2)\overline{L}, \quad \overline{L} = \frac{L_0 + L}{2};$$
 (2.8)

(A4) $\nabla^2 F$ is α -center-Hölder on V at x^* with constant K_0 , i.e.

$$\|\nabla^2 F(x) - \nabla^2 F(x^*)\| \le K_0 \|x - x^*\|^{\alpha} \text{ for all } x \in V;$$
 (2.9)

(A5) The application

$$\left[F(x^*) + \nabla F(x^*)(\cdot - x^*) + \frac{1}{2} \nabla^2 F(x^*)(\cdot - x^*)^2 + G(\cdot) \right]^{-1}$$
 (2.10)

is M-pseudo-Lipschitz around $(0, x^*)$ and G has closed graph.

We can now compare our hypotheses with the corresponding ones in [9]:

Remark 2.3. In general

$$K_0 \le K, \quad L_0 \le L, \tag{2.11}$$

hold in general and $\frac{K}{K_0}$ can be arbitrarily large [1], [2]. If $K_0 = K$ our hypotheses reduce to the ones in [9]. Otherwise our hypotheses can be used to improve the results in [9] as stated in the Introduction. Note that in practice the computation of K requires that of K_0 . That is the computational cost of our hypotheses (A1)–(A5) is the same as the corresponding one in [9] using (A1)–(A3) and (A5).

3. Local convergence analysis of method (1.2)

We will follow the proof routine in [9] but we will also stretch the differences where the really needed condition (2.9) is used instead of the stronger (2.7) used in [9].

We state the main local convergence result for method (1.2):

Theorem 3.1. Let x^* be a solution of (1.1). Under hypotheses (A1)–(A5) and for

$$c > \frac{MK}{(\alpha+1)(\alpha+1)} \tag{3.1}$$

there exists $\delta > 0$ such that for every starting guess $x_0 \in U(x^*, \delta)$ there exists a sequence $\{x_n\}$ $(n \ge 0)$ generated by method (1.2) satisfying

$$||x_{n+1} - x^*|| \le c||x_n - x^*||^{2+\alpha} \quad (n \ge 0).$$
 (3.2)

In order for us to prove this theorem we first need some notations. Let us define the set-valued map Q from X to the subsets of Y by

$$Q(x) = F(x^*) + \nabla F(x^*)(x - x^*) + \frac{1}{2}\nabla^2 F(x^*)(x - x^*) + G(x).$$
 (3.3)

Let

$$Z_n(x) = F(x^*) + \nabla F(x^*)(x - x^*) + \frac{1}{2}\nabla^2 F(x^*)(x - x^*)^2 - F(x_n) - \nabla F(x_n)(x - x_n) - \frac{1}{2}\nabla^2 F(x_n)(x - x_n)^2,$$
(3.4)

and define $T_n: X \to Y$ by

$$T_n(x) = Q^{-1}[Z_n(x)].$$
 (3.5)

Clearly x_1 is a fixed point of T_0 if and only if:

$$F(x^*) + \nabla F(x^*)(x_1 - x^*) + \frac{1}{2}\nabla^2 F(x^*)(x_1 - x^*) - F(x_0)$$
$$-\nabla F(x_0)(x_1 - x_0) - \frac{1}{2}\nabla^2 F(x_0)(x_1 - x_0)^2 \in Q(x_1), \tag{3.6}$$

or equivalently

$$o \in F(x_0) + \nabla F(x_0)(x_1 - x_0) + \frac{1}{2}\nabla^2 F(x_0)(x_1 - x_0)^2 + G(x_1).$$
 (3.7)

We need the proposition:

Proposition 3.2. Under the hypotheses of Theorem 3.1, there exists $\delta > 0$ such that for all $x_0 \in U(x^*, \delta)$ $(x_0 \neq x^*)$, the map T_0 has a fixed point x_1 in $U(x^*, \delta)$.

Proof. By (A5) there exist positive numbers a and b such that

$$e\left(Q^{-1}(y_1) \cap U(x^*, a), Q^{-1}(y_2)\right) \le M\|y_1 - y_2\|, \text{ for all } y_1, y_2 \in U(0, b).$$
 (3.8)

Choose $\delta > 0$ such that

$$\delta < \delta_0, \tag{3.9}$$

where

$$\delta_0 = \min \left\{ a, \left[\frac{b(\alpha+1)(\alpha+2)}{K_0 + K2^{2+\alpha}} \right]^{\frac{1}{2+\alpha}}, \frac{(\alpha+1)(\alpha+2)}{MK} - \frac{1}{c}, \frac{1}{1+\sqrt[\alpha]{c}} \right\}.$$
 (3.10)

We shall show condition (2.4) and (2.5) of Lemma 2.2 hold true for $p = x^*$, T being T_0 and r and λ parameters to be determined.

We first have

$$\operatorname{dist}(x^*, T_0(x^*)) \le e\left(Q^{-1}(0) \cap U(x^*, \delta), T_0(x^*)\right). \tag{3.11}$$

Using (2.7), (3.4), and (3.9) we obtain in turn:

$$||Z_{0}(x^{*})|| = ||F(x^{*}) - F(x_{0}) - \nabla F(x_{0})(x^{*} - x_{0}) - \frac{1}{2}\nabla^{2}F(x_{0})(x^{*} - x_{0})^{2}||$$

$$= ||\int_{0}^{1} (1 - t)\nabla^{2}F(x_{0} + t(x^{*} - x_{0}))(x^{*} - x_{0})^{2}dt$$

$$- \frac{1}{2}\nabla^{2}F(x_{0})(x^{*} - x_{0})^{2}||$$

$$\leq K|\int_{0}^{1} (1 - t)t^{\alpha}dt| ||x^{*} - x_{0}||^{2+\alpha}$$

$$= \frac{K}{(\alpha + 1)(\alpha + 2)}||x^{*} - x_{0}||^{2+\alpha} < b.$$
(3.12)

It follows from (3.8):

$$e(Q^{-1}(0) \cap U(x^*, \delta), T_0(x^*)) = e(Q^{-1}(0) \cap U(x^*, \delta), Q^{-1}[T_0(x^*)])$$

$$\leq \frac{MK}{(\alpha + 1)(\alpha + 2)} ||x_0 - x^*||^{2 + \alpha}$$
(3.13)

and by (3.11)

$$\operatorname{dist}(x^*, T_0(x^*)) \le \frac{MK}{(\alpha+1)(\alpha+2)} \|x^* - x_0\|^{2+\alpha}.$$
 (3.14)

Moreover by (3.9)

$$\operatorname{dist}(x^*, T_0(x^*)) < c \left[1 - \frac{MK\delta}{(\alpha + 1)(\alpha + 2)} \right] \|x^* - x_0\|^{2+\alpha}, \tag{3.15}$$

since,

$$c\left[1 - \frac{MK\delta}{(\alpha+1)(\alpha+2)}\right] > \frac{MK}{(\alpha+1)(\alpha+2)}.$$
 (3.16)

Note that by the choice of c

$$\frac{MK\delta}{(\alpha+1)(\alpha+2)} < 1. \tag{3.17}$$

By setting $p = x^*$, $\lambda = \frac{MK\delta}{(\alpha+1)(\alpha+2)}$ and $r = r_0 = c\|x_0 - x^*\|^{2+\alpha}$ we deduce (2.4). We shall show (2.5). We have $r_0 \le \delta < a$, since $\delta \le \frac{1}{1+\sqrt[\alpha]{c}}$ for $\|x_0 - x^*\| \le \delta$.

In view of (2.7), (2.9) and (3.4) we can obtain in turn

$$||Z_{0}(x)|| \leq \left| |F(x^{*}) - F(x) + \nabla F(x^{*})(x - x^{*}) + \frac{1}{2}\nabla^{2}F(x^{*})(x - x^{*})^{2} \right|$$

$$+ \left| |F(x) - F(x_{0}) - \nabla F(x_{0})(x - x_{0}) - \frac{1}{2}\nabla^{2}F(x_{0})(x - x_{0})^{2} \right|$$

$$\leq \frac{K_{0}}{(\alpha + 1)(\alpha + 2)} ||x - x^{*}||^{2 + \alpha} + \frac{K}{(\alpha + 1)(\alpha + 2)} ||x - x_{0}||^{2 + \alpha}$$

$$\leq \frac{K_{0}}{(\alpha + 1)(\alpha + 2)} ||x - x^{*}||^{2 + \alpha}$$

$$+ \frac{K}{(\alpha + 1)(\alpha + 2)} (||x - x^{*}|| + ||x_{0} - x^{*}||)^{2 + \alpha}$$

$$\leq \frac{(K_{0} + K \cdot 2^{2 + \alpha})\delta^{2 + \alpha}}{(\alpha + 1)(\alpha + 2)} \leq b,$$

$$(3.18)$$

and $Z_0(x) \in U(0,b)$. That is for all $u, v \in U(x^*, r_0)$ we have

$$e(T_0(u) \cap U(x^*, r_0), T_0(v))$$

$$\leq e(T_{0}(u) \cap U(x^{*}, \delta), T_{0}(v)) \leq M \|Z_{0}(u) - Z_{0}(v)\|
\leq M \|\nabla F(x^{*})(u - v) - \nabla F(x_{0})(u - v) + \frac{1}{2}\nabla^{2}F(x^{*})(u - v + v - u)^{2}
- \frac{1}{2}\nabla^{2}F(x^{*})(v - x^{*})^{2} + \frac{1}{2}\nabla^{2}F(x_{0})(v - x_{0})^{2}
- \frac{1}{2}\nabla^{2}F(x_{0})(u - v + v - x_{0})^{2} \| \leq 5M\overline{L}\delta\|u - v\|,$$
(3.19)

which shows (2.5). It follows by Lemma 2.2 $x_1 \in U(x^*, r_0)$ is a fixed point of T_0 .

That completes the proof of Proposition 3.2.

Proof of Theorem 3.1. We have $x_1 \in U(x^*, r_0)$. That is

$$||x_1 - x^*|| \le r_0 = c||x_0 - x^*||^{2+\alpha}.$$
(3.20)

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We continue using induction on $n \geq 0$. Set $p = x^*$, $\lambda = \frac{MK\delta}{(\alpha+1)(\alpha+2)}$ and $r_n = c\|x_n - x^*\|^{2+\alpha}$ to obtain again from the application of Proposition 3.2 to T_n the existence of a fixed point x_{n+1} of T_n in $U(x^*, r_n)$, which implies (3.2). That completes the proof of Theorem 3.1.

Corollary 3.3. Let x^* be a simple solution of (1.1). Under assumptions (A1)–(A5) for

$$c > \frac{MK}{(\alpha+1)(\alpha+2)} = c_0 \tag{3.21}$$

there exists $\delta > 0$ such that any sequence $\{x_n\}$ generated by (1.2) with $x_n \in U(x^*, \delta)$ satisfies (3.2).

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Proof. Let $\delta > 0$ be a number satisfying (3.9) and

$$\delta < \delta_1, \tag{3.22}$$

where,

$$\delta_1 = \min \left\{ \frac{1}{3M\overline{L}}, \frac{(\alpha+1)(\alpha+2)c - MK}{3(\alpha+1)(\alpha+2)cM\overline{L}} \right\}.$$
 (3.23)

We assume without loss of generality that x^* is a unique solution of (1.1) in a certain neighborhood of x^* , since x^* is a simple zero of (1.1). Let us choose it to be $U(x^*, \delta)$. Set $x^* = Q^{-1}(0) \cap U(x^*, \delta)$. By Theorem 3.1

$$x_{n+1} = Q^{-1}[Z_n(x_{n+1})].$$

In view of (2.2), (2.3), (2.7) and (2.8) we obtain in turn:

$$\operatorname{dist}(x_{n+1}, Q^{-1}(0)) = \|x_{n+1} - x^*\| \\ \leq e(Q^{-1}[Z_n(x_{n+1})] \cap U(x^*, \delta), Q^{-1}(0)) \leq M \|Z_n(x_{n+1})\| \\ \leq M \|F(x^*) + \nabla F(x^*)(x_{n+1} - x^*) + \frac{1}{2}\nabla^2 F(x^*)(x_{n+1} - x^*)^2 \\ - F(x_n) - \nabla F(x_n)(x_{n+1} - x_n) - \frac{1}{2}\nabla^2 F(x_n)(x_{n+1} - x_n)^2 \| \\ \leq M \|F(x^*) + \nabla F(x^*)(x_{n+1} - x^*) + \frac{1}{2}\nabla^2 F(x^*)(x_{n+1} - x^*)^2 \\ - F(x_n) - \nabla F(x_n)(x_{n+1} - x^* + x^* - x_n) \\ - \frac{1}{2}\nabla^2 F(x_n)(x_{n+1} - x^* + x^* - x_n)^2 \| \\ \leq M \left[\frac{K_0}{(\alpha + 1)(\alpha + 2)} \|x^* - x_n\|^{2+\alpha} + 3\overline{L}\delta \|x_{n+1} - x^*\| \right], \quad (3.24)$$

or

$$||x_{n+1} - x^*|| \le \frac{MK}{(\alpha + 1)(\alpha + 2)(1 - 3M\overline{L}\delta)} ||x_n - x^*||^{2+\alpha}$$
$$< c||x_n - x^*||^{2+\alpha}.$$

That completes the proof of Corollary 3.3.

Remark 3.4. If $L_0 = L$ and $K_0 = K$, then our results are reduced to the corresponding ones in [9]. Otherwise they constitute an improvement. Indeed, let us denote by $\overline{\delta}_0$, $\overline{\delta}_1$ parameters obtained from δ_0 and δ_1 respectively by replacing K_0 and L_0 by K and L respectively. Then, we get

$$\overline{\delta}_0 \le \delta_0 \tag{3.25}$$

and

$$\overline{\delta}_1 \le \delta_1. \tag{3.26}$$

That is we can obtain a larger convergence radius for method (1.2), which implies that a wider choice of initial choices x_0 becomes available, and finer error bounds on the distances $||x_n - x^*||$ $(n \ge 0)$. These observations are important in computational mathematics [1], [2], [6].

Remark 3.5. The local results obtained here can be used to solve equations where F'' satisfies the autonomous differential equation [1], [2]

$$F''(x) = P(F(x)), (3.27)$$

where $P: Y \to X$ is a known continuous operator. Since $F''(x^*) = P(F(x^*)) = P(0)$, we can apply our results without actually knowing the solution x^* of equation (1.1).

We complete this study with two numerical examples where we show that strict inequality can hold in (2.11).

Example 3.6. Let $X = Y = \mathbf{R}$, $x^* = 0$, and define F on U(0,1) by

$$F(x) = e^x - x. (3.28)$$

It can easily be seen that

$$\alpha = 1, L_0 = 1, L = K = e \text{ and } K_0 = e - 1.$$
 (3.29)

Example 3.7. Let $X = Y = \mathbf{R}$, $x^* = \frac{9}{4}$, $U(x^*, r) \subset D = [.81, 6.25]$, and define function F on D by

$$F(x) = \frac{4}{15}x^{5/2} - \frac{1}{2}x^2. {(3.30)}$$

We obtain

$$\alpha = \frac{1}{2}, \ L_0 = \frac{1}{2}, \ L = \sqrt{6.25} - 1, \ K_0 = \frac{1}{2} \text{ and } K = 1.$$
 (3.31)

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